Joint distributions for total lengths of shortest-path trees in telecommunication networks

David Neuhäuser \cdot Christian Hirsch \cdot Catherine Gloaguen \cdot Volker Schmidt

Received: date / Accepted: date

Abstract Shortest-path trees play an important role in the field of optimising fixed-access telecommunication networks with respect to costs and capacities. Distributional properties of the corresponding two half-trees originating from the root of such a tree are of special interest for engineers. In the present paper, we derive parametric approximation formulas for the marginal density functions of the total lengths of both half-trees. Besides, a parametric copula is used in order to combine the marginal distributions of these functionals to a bivariate joint distribution as, naturally, the total lengths of the half-trees are not independent random variables. Asymptotic results for infinitely sparse and infinitely dense networks are discussed as well.

Keywords Shortest-path tree \cdot Palm calculus \cdot parametric copula \cdot tree length \cdot network planning \cdot pseudo-maximum-likelihood \cdot stochastic geometry

Mathematics Subject Classification (2000) 60D05 · 65C99 · 62E17

1 Introduction

The Stochastic Subscriber Line Model, as described in [2], [4] and [14], is a powerful tool to model access networks in urban areas. In [9], it has recently been extended by so-called *shortest-path trees* which allow engineers and telecommunication companies such as Orange Labs not only for estimating cable lengths but

This work was supported by Orange Labs through Research grant No. 46146063-9241. Christian Hirsch was supported by a research grant from DFG Research Training Group 1100 at Ulm University. Parts of the numerical results were obtained by the help of Jan Sommer.

D. Neuhäuser, C. Hirsch and V. Schmidt Ulm University, Helmholtzstraße 18, 89069 Ulm, Germany Tel.: +49-(0)7315023555 E-mail: david.neuhaeuser@uni-ulm.de

C. Gloaguen Orange Labs, 38-40 rue du Général Leclerc, 92794 Issy-Moulineaux Cedex 9, France Tel.: +33-(0)
145296441 also for calculating capacity demands in telecommunication networks. Since the geometry of such trees can be extremely tricky and complex, the idea of attacking this problem is to build models of increasing elaborateness which enable to describe shortest-path trees in further and further details. A first step towards this goal has been done in [9], where we focused on the bivariate distribution of the lengths of the main branches of each half-tree. The present paper can be seen as a continuation and extension of this research process. Consequently, we study further important functionals of the shortest-path tree, namely the total lengths of the corresponding half-trees.

The paper is organised as follows. In Section 2, we introduce the mathematical tools which allow for modelling telecommunication networks by means of stochastic geometry. In particular, random tessellations, point processes and Palm calculus play an important role in this context. Sections 3 and 4 deal with modelling the total lengths of the half-trees in the shortest-path tree, where we proceed in a similar way as in [9], using parametric approximation formulas for the marginal distributions of the total lengths of the half-trees. However, in contrast to the situation considered in [9], it now turns out that the marginal distributions investigated in the present paper are much more difficult to handle and as a consequence, the fitting procedure is no longer just straightforward. Furthermore, we employ parametric copulas in order to combine these univariate distributions as the half-trees (and therefore their total lengths) cannot be assumed to be independent. Asymptotic results for infinitely sparse and infinitely dense networks are discussed as well. Then, in Section 5, we validate the model in two ways. On the one hand, we perform a visual validation which is comparable to the one considered in [9]. Additionally, on the other hand, we also provide a statistically rigorous distributional test for our model based on a multivariate version of the Wald-Wolfowitz test introduced in [3]. Section 6 finally concludes the paper and gives an outlook to possible future research.

2 Mathematical Preliminaries

As already mentioned in the introduction, the *Stochastic Subscriber Line Model* (SSLM) uses tools of stochastic geometry to model copper or optical fibre networks in urban but also rural regions. The SSLM consists of four layers, which will be -for the convenience of the reader- briefly discussed in the following.

2.1 Random Tessellations of Poisson Type

The first layer of the SSLM concerns the geometrical support. With the intention to reach as many customers as possible, cables and fibres are installed along the road system of cities and towns. Modelling road systems in the SSLM is carried out by the usage of connected, stationary random graphs T, such as various types of random tessellations or β -skeletons, see [10]. The present paper is restricted to random tessellations based upon a homogeneous Poisson point process in \mathbb{R}^2 , namely Poisson-Voronoi tessellations (PVT), Poisson-Delaunay tessellations (PDT) as well as Poisson line tessellations (PLT). To get more information about these well-known random geometric graphs, the reader is referred to [12] and [13].

2.2 Cox Processes Representing Network Nodes

The second layer of the SSLM consists of the placement of the network components. Note that we consider two-hierarchy-level networks, i.e., investigated path properties are always between a higher-level component (HLC) and a lower-level component (LLC), such as paths between service area interfaces and subscribers. All network components are assumed to be located on the underlying infrastructure represented by a stationary random tessellation T. In particular, we make use of a stationary Cox process $X_H = \{X_{H,i}\}$ in order to model the locations of HLC. The random intensity measure of X_H is concentrated on the edge set $T^{(1)}$ of the tessellation T and is proportional to the one-dimensional Hausdorff measure ν_1 on $T^{(1)}$. More precisely, we have $\mathbb{E}X_H(B) = \lambda_\ell \mathbb{E}\nu_1(B \cap T^{(1)})$ for each Borel set $B \subset \mathbb{R}^2$ and linear intensity $\lambda_{\ell} > 0$. Note that the planar intensity of X_H is thus given by $\lambda_H = \lambda_\ell \gamma$ where $\gamma = \mathbb{E}\nu_1([0,1]^2 \cap T^{(1)})$ denotes the total length of $T^{(1)}$ per unit area. For additional information about point processes, the reader can consult e.g. [1] and [6]. Note that if the intensity of the LLC is sufficiently high, then the corresponding point process differs only negligibly from the underlying road system. Due to this approximation, we only consider certain sub-networks defined by the HLC.

2.3 Cox-Voronoi Cells as Serving Zones and Typical Cells

Although we have the underlying infrastructure and the network components modelled, we still have to specify how HLC and LLC – any point of the underlying infrastructure in the present setting – are connected to each other. The third layer of the SSLM, the topological part, defines these connection rules. We link each LLC to its nearest HLC in the Euclidean sense. More formally, we define the tessellation $\{\Xi_{H,i}\}_{i\geq 1}$ as the Voronoi tessellation generated by the points of the Cox process $X_H = \{X_{H,i}\}$ of higher-level components (also called Cox-Voronoi tessellation). Then, each LLC located inside a so-called serving zone $\Xi_{H,i}$ is connected to its corresponding HLC $X_{H,i}$ along the edges of the underlying tessellation T. Nodes are connected via shortest paths, i.e., the distance between LLC and corresponding HLC measured along $T^{(1)}$ is the smallest possible one. For further details on connection rules, the reader is referred to [10].

Note that the supply of the network for one single user is often not as important as the expected network quality averaged over all users in a large area. Palm calculus and Palm distributions provide a convenient formalisation of this problem. Therefore, the Palm version X_H^* of X_H is of special interest in this context. Its distribution can be interpreted as conditional distribution of X_H given that there is a HLC located at the origin $o = (0,0)^\top \in \mathbb{R}^2$. More formally, the distribution of X_H^* is determined by the representation formula

$$\mathbb{E}g(X_H^*) = \frac{1}{\lambda_H} \mathbb{E}\sum_{i: X_{H,i} \in [0,1]^2} g(\{X_{H,n}\} - X_{H,i})$$

where $g: \mathbb{L} \to [0, \infty)$ is an arbitrary measurable function and \mathbb{L} denotes the family of all locally finite sets of \mathbb{R}^2 . Furthermore, we define the *typical serving zone* Ξ_H^* of X_H as the Voronoi cell whose cell centre is located at the origin o in the Voronoi tessellation constructed from X_H^* , i.e.,

$$\Xi_{H}^{*} = \{ x \in \mathbb{R}^{2} : \|x\| \le \|x - X_{H,j}^{*}\| \text{ for all } j \ge 1 \}.$$

Besides, in order to construct the shortest-path tree, we are interested in a further characteristic of the Voronoi tessellation constructed from X_H^* , the so-called *typical segment system* S_H^* . To define this, let $S_{H,i} = \Xi_{H,i} \cap T^{(1)}$ denote the segment system of the serving zone $\Xi_{H,i}$ which belongs to the corresponding HLC $X_{H,i}$. Then, the typical segment system S_H^* is defined as the typical mark of the point process of higher-level nodes $X_{H,i}$ marked with their corresponding segment systems $S_{H,i}$. For definitions and details on marked point processes, Palm mark distribution and typical marks, the reader is referred to [1] and [13].

2.4 Shortest-Path Tree Representing the Inner Life of a Serving Zone

Under our assumption on the intensity of LLC, the fourth layer of the SSLM, the so-called shortest-path tree G, is roughly speaking just a rearrangement of the typical segment system S_H^* . Following the paths from all points in S_H^* to the origin o in the typical serving zone Ξ_H^* induces a natural tree structure. Note that these paths can sometimes leave Ξ_H^* . For further details on this tree, see [9]. Besides, one should bear in mind that G can be subdivided into two subtrees, say G_1^h and G_2^h , as the origin o (representing the root of the tree) lies with probability 1 in the interior of a segment of S_H^* . Note that G_1^h is characterised as the half-tree containing the longest branch of the shortest-path tree. For an illustration of the situation, see Figure 2.1.



Fig. 2.1 Typical cell Ξ_H^* (dot-dashed) and typical segment system S_H^* (solid) on the left-hand side and corresponding shortest path tree G with its half-trees G_1^h (solid) and G_2^h (dashed) on the right-hand side

3 Modelling Approach

One specific functional of G which has already been discussed in our previous work [9] is the so-called skeletal backbone, i.e., the main branches in the half-tree G_1^h

and G_2^h . In the present paper, we want to go one step further and examine the total lengths of G_1^h and G_2^h . The goal is to derive a general approach to model the joint bivariate distribution of the functional $I = (I_1, I_2)$, where

$$I_i = \nu_1(G_i^h), \quad i \in \{1, 2\}.$$
 (3.1)

3.1 Bivariate Copulas

Note that, analogously to the skeletal backbone, the random functionals considered in (3.1) are certainly not independent. Thus, they prevent the usage of a bivariate distribution function given by

$$F_{(I_1,I_2)}(x_1,x_2) = F_{I_1}(x_1) \cdot F_{I_2}(x_2)$$

In this context, copulas provide a powerful framework to model the correlation structure of the functionals I_1, I_2 , and this methodology has already been successfully applied in [9]. For the convenience of the reader, we briefly recall the definition of a bivariate copula. A function $C : [0,1]^2 \to [0,1]$ is called *bivariate copula* if there exists a probability space $(\Omega, \mathcal{F}, \mathbb{P})$ supporting a random vector $U = (U_1, U_2)$ such that

$$C(u_1, u_2) = \mathbb{P}(U_1 \le u_1, U_2 \le u_2), \quad u_1, u_2 \in [0, 1],$$

and $U_i \sim U[0,1]$ for $i \in \{1,2\}$. For further details on copulas, the reader is referred to [7] and [8]. Now, the bivariate joint distribution function of the random vector $I = (I_1, I_2)$ can be written as

$$F_I(x) = C_I(F_{I_1}(x_1), F_{I_2}(x_2)),$$

where $x = (x_1, x_2), x_1, x_2 > 0$. In order to obtain a parsimonious parametric model applicable for any values of the linear intensity λ_{ℓ} of HLC and the length intensity γ of T, we utilise a family of parametric copulas. One possible tool for fitting parametric models to given datasets is the maximum-likelihood method. Suppose we consider parametric models $F_{I_1}(\cdot;\eta_1), F_{I_2}(\cdot;\eta_2)$ and $C_I(\cdot;\eta)$ with parameter vectors η_1, η_2 and η for the marginals as well as for the copula, respectively, and assume an i.i.d. sample $I^{(j)} = (I_1^{(j)}, I_2^{(j)}), j = 1, \ldots, n$ where n denotes the sample size. Then, the log-likelihood function loglik₁ has representation

$$\log \lim_{I_1} (\eta_1 \eta_2, \eta)$$

$$= \sum_{j=1}^n \left(\log f_{I_1}(I_1^{(j)}; \eta_1) + \log f_{I_2}(I_2^{(j)}; \eta_2) + \log \left[c_I \left(F_{I_1}(I_1^{(j)}; \eta_1), F_{I_2}(I_2^{(j)}; \eta_2); \eta \right) \right] \right),$$

$$(3.2)$$

where $c_I(\cdot;\eta)$ denotes the density function of $C_I(\cdot;\eta)$. An uncomfortable disadvantage of this tool is that while computing maximum-likelihood estimates of the parameters of the bivariate distributions describing I_1 and I_2 , numerical problems can occur due to the inherent optimisation problem that involves several parameters. In the following, we therefore make use of a *parametric pseudo-maximumlikelihood approach* to avoid such difficulties. In particular, the optimisation problem can be subdivided into two steps which are considered separately. First, we determine the univariate marginal distributions of I_1 and I_2 . Second, a parametric copula is fitted in order to model their correlation structure. For further details on the pseudo-maximum-likelihood approach, see [9] and especially [11].

3.2 Fitting Procedure for the Marginal Densities

The fitting procedure for the marginal density of I_1 is quite different from the procedure for I_2 . On the one hand, in order to fit an approximative parametric representation formula for the density of I_1 , we can proceed by using ordinary maximum-likelihood estimation and by manual choice of an eligible class of commonly used distributions. Looking at the histograms of the datasets, we can use e.g. gamma distributions, Weibull distributions, etc., see Figure 3.1. Results are provided in Section 4. Note that similar to [15], a certain scaling invariance in our model can be shown for underlying PVT, PDT or PLT and therefore it suffices to investigate the dependence of the distribution of I_i on the scaling parameter $\kappa = \frac{\gamma}{\lambda_\ell}$.



Fig. 3.1 Histograms of the functional I_1 with underlying PVT for $\kappa = 20$ (left) and with underlying PDT for $\kappa = 50$ (right)

Finding an approximative parametric representation formula for the density of I_2 on the other hand is a much more challenging task. In Figure 3.2, the mindful reader detects a very high peak at the left hand side of each histogram which makes a density fitting by commonly used methods and parametric distributions (as we did in [9]) nearly impossible. This effect is caused by the fact that if the origin, representing the root of G, is located close to the boundary of the typical serving zone Ξ_H^* , the number and lengths of segments in G_2^h are very small. This, in turn, causes a very small value of I_2 . The effect decreases for increasing values of



Fig. 3.2 Histograms of the functional I_2 with underlying PVT for $\kappa = 20$ (left) and with underlying PDT and $\kappa = 50$ (right)

 κ and vanishes for κ sufficiently large as the network becomes denser and denser. Figures 3.3 and 3.4 show two constellations, where the origin is located close to the boundary and deeply in the interior of the typical serving zone Ξ_H^* , respectively. Furthermore, this effect depends on the type of the underlying tessellation T. Therefore, we decided to subdivide the range R of the scaling parameter κ into two disjoint intervals R_{peak} , where this effect can be observed, and $R \setminus R_{\text{peak}}$, where it does not appear. Then, we fit an approximative parametric density for I_2 for each of these two intervals separately. In particular, we have the following possible constellations which are shown in Table 3.1.

Table 3.1 Subintervals R_{peak} and $R \setminus R_{\mathsf{peak}}$ of κ , depending on the type of the underlying tessellation T

T	R_{peak}	$R\setminus R_{peak}$
PVT	[10, 40]	(40, 1000]
PDT	[10, 90]	(90, 1000]
PLT	Ø	[10, 1000]

So as to manage the difficulties caused by scenarios where the origin is located closely to the boundary of Ξ_H^* in the range R_{peak} of κ , we subdivide the data into two parts: scenarios where G_2^h consists of one single segment and scenarios where G_2^h consists of several segments. For each of the two cases, we fit parametric densities via the ordinary maximum-likelihood method. The parametric density function in R_{peak} is therefore a mixture of these two densities with a mixing parameter $\rho \in [0, 1]$ which denotes the probability that G_2^h consists of several segments. It can be easily estimated by taking the ratio of the number of observed scenarios



Fig. 3.3 Scenario 1: G_2^h (black) consisting of a single segment in PVT case (left) and PDT case (right)



Fig. 3.4 Scenario 2: G_2^h (black) consisting of several segments in PVT case (left) and PDT case (right)

where G_2^h consists of several segments and the total number of realisations in the dataset. This kind of attacking the 'origin is close to boundary problem' turns out to provide very good fitting results, see Section 5. In the range $R \setminus R_{peak}$, where κ is sufficiently large, it is quite easy to fit a parametric density via the maximum-likelihood method. Afterwards, in order to obtain the parametric density for the whole range R of κ , we add the two densities multiplied by the indicator functions of their corresponding ranges R_{peak} and $R \setminus R_{peak}$ (see Section 4.1.2). Note that in the PLT case, we have no subdivision of R, i.e., $R = R \setminus R_{peak}$.

We also remark that the methodology of separately considering the scenario where the origin is closely located to the boundary can also be useful in the analysis of further important quantities of G. For instance, in [9], it is observed that the distribution of the longest branch of G_2^h is of bimodal type where the location of the first mode is mainly determined by this 'boundary scenario'. However, in [9], standard statistical methods were sufficient to obtain parametric density functions which provide a satisfactory approximation to the data.

3.3 Fitting Procedure for the Copula

The copula types considered in the present paper are the t-copula, the Gaussian copula and the Archimedean copulas Clayton, Gumbel, Joe, Ali-Mikhail-Haq as well as Frank (for further explanations, see [7] and [8]). The fitting procedure for the copula is done by means of Akaike's information criterion defined as

$$AIC = 2\left(p - \text{loglik}_2(\hat{\eta})\right), \tag{3.3}$$

where p denotes the number of parameters in the model and $\text{loglik}_2(\hat{\eta})$ is the maximised log-likelihood where the log-likelihood function is given by

$$\operatorname{loglik}_{2}(\eta) = \sum_{j=1}^{n} \log \left[c_{I} \left(\hat{F}_{I_{1}}(I_{1}^{(j)}), \hat{F}_{I_{2}}(I_{2}^{(j)}); \eta \right) \right].$$
(3.4)

Note that (3.4) is obtained from (3.2) by omitting summands not depending on η and by replacing the marginal distribution functions F_{I_i} by their empirical distribution functions \hat{F}_{I_i} . The copula type which minimises (3.3) is chosen to work with.

4 Results

We now present results for the joint bivariate distribution of $I = (I_1, I_2)$ which is obtained by the parametric pseudo-maximum-likelihood approach discussed in Section 3.

4.1 Parametric Approximation Formulas for the Marginal Density Functions

Due to the different approaches when fitting parametric formulas to the density functions f_{I_1} and f_{I_2} , we obtain quite different results for the half-trees G_1^h and G_2^h . For f_{I_1} we can use the same type of distribution for all three types of the underlying tessellation T whereas for f_{I_2} , we have to distinguish between the types of T. In particular, we obtain the following results.

4.1.1 Parametric Approximation Formula for f_{I_1}

For all three types of the underlying tessellation T, namely PVT, PDT and PLT, it approximately holds that $I_1 \sim Gamma(k, \lambda)$ with some shape parameter k > 0and some scale parameter $\lambda > 0$. In particular, the density function of I_1 is given by

$$f_{I_1}(x) = \frac{1}{\lambda^k} \frac{1}{\Gamma(k)} x^{k-1} e^{-\frac{x}{\lambda}},$$

where $\Gamma(\cdot)$ denotes the gamma function and x > 0. Note that the parameters k and λ obtained by the fitting procedure both depend on the scaling parameter κ and on the type of T.

4.1.2 Parametric Approximation Formula for f_{I_2}

Concerning approximation formulas for f_{I_2} , we have to distinguish between the different types of tessellation. The approximation formulas for f_{I_2} are based on the following three types of distributions which are given by

- 1. the lognormal distribution with density $f_{logN}(x) = \frac{1}{\sqrt{2\pi}x\sigma} \exp\left(-\frac{(\log x-\nu)^2}{2\sigma^2}\right)$ for some $\nu \in \mathbb{R}$ and $\sigma, x > 0$ (short: $logN(\nu, \sigma)$),
- 2. the Nakagami distribution with density $f_{Naka}(x) = \frac{2\mu^{\mu}x^{2\mu-1}}{\Gamma(\mu)\Omega^{\mu}} \exp\left(-\frac{\mu}{\Omega}x^2\right)$ for some $\mu \geq \frac{1}{2}$ and $\Omega, x > 0$ (short: $Naka(\mu, \Omega)$),
- 3. the Weibull distribution with density $f_{Wei}(x) = \frac{\ell}{\theta} \left(\frac{x}{\theta}\right)^{\ell-1} \exp\left(-\left(\frac{x}{\theta}\right)^{\ell}\right)$ for some $\ell, \theta > 0$ and $x \ge 0$ (short: $Wei(\ell, \theta)$).

Table 4.1 shows the resulting approximative distributions for I_2 .

Table 4.1 Approximative distributions for I_2

T	distribution in R_{peak}	distribution in $R \setminus R_{peak}$
PVT PDT PLT	$\rho \cdot logN(\nu, \sigma) + (1 - \rho) \cdot Naka(\mu, \Omega)$ $\rho \cdot logN(\nu, \sigma) + (1 - \rho) \cdot Naka(\mu, \Omega)$	$Wei(\ell, heta) \ Wei(\ell, heta) \ Wei(\ell, heta) \ Wei(\ell, heta)$

Note that, analogously to the I_1 -case, the parameters $\rho, \nu, \sigma, \mu, \Omega, \ell$ and θ depend on both κ and the type of T.

4.2 Choosing a Suitable Parametric Copula

Among the considered copula types mentioned in Section 3.3, the Gaussian copula is the one which minimises (3.3). It is given by

$$C_{\Sigma}^{Gauss}(u,v) = \Phi_{\Sigma} \left(\Phi^{-1}(u), \Phi^{-1}(v) \right),$$

where Φ_{Σ} denotes the joint cumulative distribution function of a bivariate normal distribution with mean vector o and covariance matrix Σ and where Φ^{-1} denotes the inverse cumulative distribution function of the one-dimensional standard normal distribution. The covariance matrix Σ with correlation coefficient $\psi \in [-1, 1]$ has representation

$$\varSigma = \begin{pmatrix} 1 & \psi \\ \psi & 1 \end{pmatrix}$$

This optimisation result is true for all three types of the underlying tessellation T. Furthermore, the copula type does not depend on the scaling parameter κ . On the other hand, the parameter ψ of the Gaussian copula depends on the type of T and κ , i.e., $\psi = \psi(T, \kappa)$. However, it turns out that the dependence of $\psi(T, \kappa)$ in κ is negligible, so that we can assume $\psi = \psi(T)$. Note that in our considered data, the total lengths of the two half-trees differ at least by 10^{-6} length units in 99.5% of all cases. This justifies the usage of a copula which is absolutely continuous with respect to the two-dimensional Lebesgue measure.

4.3 Joint Distribution for Infinitely Sparse and Infinitely Dense Road Systems

In addition to the parametric approximation results obtained in Sections 4.1 and 4.2, we also provide a description of the joint distribution of I for infinitely sparse and infinitely dense networks. Limit scenarios where the underlying road system becomes infinitely sparse or infinitely dense are of special interest since the extracted data of the typical segment system is available for a large but only finite range of κ . For very small κ , fitting methods are unstable and for increasing values of κ , Monte Carlo simulations become very time consuming.

4.3.1 Infinitely Sparse Networks

First, we consider the case of infinitely sparse networks, i.e., $\lambda_{\ell} \to \infty$ and $\gamma = 1$ (and therefore $\kappa \to 0$). In this scenario, the typical segment system S_H^* consists of the union of two segments, say L_1 and L_2 , with independent and exponentially distributed lengths joined at the origin. In particular, we have that $\nu_1(L_i) \sim Exp(2\lambda_{\ell}), i \in \{1,2\}$. We thus obtain $\mathbb{P}(I_1 \leq x) = \mathbb{P}(\max\{\nu_1(L_1), \nu_1(L_2)\} \leq x) = \mathbb{P}(\nu_1(L_1) \leq x, \nu_1(L_2) \leq x) = (1 - \exp(-2\lambda_{\ell}x))^2$ and therefore

$$f_{I_1}(x) = 4\lambda_{\ell} \, \left(\exp\left(-2\lambda_{\ell}x\right) - \exp\left(-4\lambda_{\ell}x\right) \right).$$

Similarly, we obtain $\mathbb{P}(I_2 \leq x) = 1 - \mathbb{P}(I_2 > x) = 1 - \mathbb{P}(\min\{\nu_1(L_1), \nu_1(L_2)\} > x) = 1 - \mathbb{P}(\nu_1(L_1) > x, \nu_1(L_2) > x) = 1 - (\exp(-2\lambda_\ell x))^2 = 1 - \exp(-4\lambda_\ell x)$ and therefore

$$f_{I_2}(x) = 4\lambda_\ell \exp\left(-4\lambda_\ell x\right)$$

To summarise, the joint distribution of $I = (I_1, I_2)$ is given by the distribution of the random vector $(\max\{V_1, V_2\}, \min\{V_1, V_2\})$, where V_1, V_2 are independent exponentially distributed random variables with parameter $2\lambda_{\ell}$.

4.3.2 Infinitely Dense Networks

Second, we provide a description of the joint distribution of I for infinitely dense networks, i.e., $\lambda_{\ell} \to 0$ and $\gamma = 1$ (and therefore $\kappa \to \infty$). In order to achieve this goal, we first note that as $\lambda_{\ell} \to 0$, the rescaled typical serving zone $\sqrt{\lambda_{\ell}} \Xi_{H,\lambda_{\ell}}^*$ at intensity λ_{ℓ} converges in distribution to a typical Poisson-Voronoi cell Ξ_{PV}^{*} . This can be heuristically explained by observing that, as the road system becomes infinitely dense, the rescaled Cox process of HLC converges to a homogeneous Poisson point process. Moreover, the boundary between the half-trees G_1^h and G_2^h asymptotically approaches the union of two rays corresponding to the asymptotic directions of these boundaries. Hence, the division of the typical serving zone induced by the half-trees can be recovered as a decomposition $\Xi_{PV}^* = A_1 \cup A_2$, where the two sets A_1, A_2 are defined by two rays whose enclosed angle only depends on the type of the underlying tessellation. In particular, as $\lambda_{\ell} \to 0$, the suitably rescaled total lengths of the half-trees converge to the areas of the two parts A_1 and A_2 . Combining these asymptotic properties, the joint distribution of the rescaled total lengths $(\lambda_{\ell}I_1, \lambda_{\ell}I_2)$ converges in distribution to the distribution of the random vector $(\nu_2(A_1), \nu_2(A_2))$, where ν_2 denotes the two-dimensional Lebesgue measure. In a forthcoming paper [5], we will provide a rigorous proof for this heuristically derived asymptotic result.

5 Validation of the Model

In the following, we give two possibilities to validate the model introduced in the present paper. The first one is rather heuristic while the second one relies on statistical tools. In particular, we used the following validation methods.

5.1 Visual Validation

A first possibility to validate our model for the functionals I_i , $i \in \{1, 2\}$ of G is a visual comparison between empirical data extracted from S_H^* on the one hand and directly simulated data on the other hand. We compare both the univariate datasets of the marginals and the bivariate datasets of $I = (I_1, I_2)$.

5.1.1 Marginal Densities

In Figure 5.1, the histograms of I_1 are plotted together with the fitted density functions of the corresponding gamma distributions for two different scenarios, namely for an underlying PVT with scaling parameter $\kappa = 250$ (left) and an underlying PDT with scaling parameter $\kappa = 50$ (right). Both densities fit to the empirical data quite well.



Fig. 5.1 Histograms of I_1 with underlying PVT for $\kappa = 250$ (left) and with underlying PDT for $\kappa = 50$ (right) together with the fitted densities according to Section 4.1.1

In Figure 5.2, we present the histograms of I_2 together with the fitted density functions of the corresponding Weibull distributions for the same scenarios as in

Figure 5.1. Both densities fit to the empirical data quite well, too. Using our suggested modelling approach, especially the difficulties due to the high peaks in the histograms for lower values of κ mentioned in Section 3 can thus obviously be handled well.



Fig. 5.2 Histograms of I_2 with underlying PVT for $\kappa = 250$ (left) and with underlying PDT for $\kappa = 50$ (right) together with the fitted densities according to Section 4.1.2

5.1.2 Joint Distribution

Figure 5.3 shows the contour plot of the empirical copula, coloured black, and the contour plot of the fitted Gaussian copula, coloured red. Only slight and negligible differences between the contour plots can be observed, which is a first hint that our fitted copula should be suitable.

Furthermore, we take a look at the shape of the empirical density function of I and the density function of the corresponding fitted bivariate Gaussian copula. Figure 5.4 shows the corresponding plots with underlying PVT and $\kappa = 75$. We can observe that empirical and simulated density plots seem to be nearly equal. In order to see if the empirical data extracted from the typical segment system S_{Ξ}^* and the data directly simulated from the Gaussian copula coincide, we take a look at the corresponding scatterplots, see Figure 5.5. The final results are very similar, so that we can conclude that the model provides realistic scenarios.



Fig. 5.3 Contour plots of the empirical copula (black) and the fitted Gaussian copula (red) for I in PVT case with $\kappa=75$



Fig. 5.4 Empirical density function (left) and fitted Gaussian copula density (right) for I in PVT case with $\kappa=75$



Fig. 5.5 Scatter plots of the empirical data (left) and directly simulated data (right) for I in PVT case with $\kappa=75$

5.2 Multivariate Wald-Wolfowitz Test

Besides a visual comparison, it is also desirable to validate the model with statistical tools, where we make use of a multivariate generalisation of the well-known univariate Wald-Wolfowitz two-sample test. This generalisation has been extensively discussed in [3]. For the convenience of the reader, we briefly recall the general settings of the test. Let $X_1, \ldots, X_n, Y_1, \ldots, Y_m \in \mathbb{R}^2$ be independent bivariate vectors and let furthermore $X_1, \ldots, X_n \sim F_X$ and $Y_1, \ldots, Y_m \sim F_Y$ for some arbitrary distribution functions F_X and F_Y . We want to test the null-hypothesis $H_0: F_X = F_Y$ against the alternative $H_1: F_X \neq F_Y$. In our case, $\{X_j\}_{1 \leq j \leq n}$ corresponds to empirical data extracted from the typical segment system S_H^* whereas $\{Y_k\}_{1 \le k \le m}$ corresponds to data simulated directly from the copula and the marginal distributions. In order to define a decision rule whether H_0 will be rejected or not, we have to take a look at the minimal spanning tree (MST) based on (the Euclidean distances of) the joint sample $X_1, \ldots, X_n, Y_1, \ldots, Y_m$. Let S denote the number of disjoint subtrees resulting from erasing all edges of MST with nodes from different samples. Additionally, let D denote the number of edge pairs that share a common node in MST, $\operatorname{Var}(S|D)$ denote the conditional variance of S given D and let N = n + m. Then, it is shown in [3] that under H_0 , $\mathbb{E}S = \frac{2nm}{N} + 1$, $\operatorname{Var}(S|D) = \frac{2nm}{N(N-1)} \left(\frac{2nm-N}{N} + \frac{D-N+2}{(N-2)(N-3)} (N(N-1) - 4nm + 2) \right) \text{ and furthermore } \frac{S-\mathbb{E}S}{\sqrt{\operatorname{Var}(S|D)}} \text{ is asymptotically } N(0,1) \text{-distributed. The null-hypothesis } H_0 \text{ is }$ therefore rejected for specific realisations x_1, \ldots, x_n of X_1, \ldots, X_n and y_1, \ldots, y_m of Y_1, \ldots, Y_m if

$$\left|\frac{S - \mathbb{E}S}{\sqrt{\operatorname{Var}(S|D)}}\right| > z_{1-\alpha/2}$$

where $z_{1-\alpha/2}$ denotes the $(1-\alpha/2)$ -quantile of the N(0,1)-distribution. In Table 5.1, the results of the multivariate generalisation of the Wald-Wolfowitz test for

various scenarios are listed. We chose n = m = 1000 and the confidence level $\delta = 1 - \alpha = 95\%$. For all considered examples of structural scenarios, H_0 is not rejected which supports our visual validation.

Table 5.1	Results	of the	Wald-	Wolfowitz	test
-----------	---------	--------	-------	-----------	------

Scenario	$\left \frac{S\!-\!\mathbb{E}S}{\sqrt{\mathrm{Var}(S D)}}\right $	$z_{0.975}$	H_0
PVT $\kappa = 40$ PVT $\kappa = 250$ PDT $\kappa = 20$ PDT $\kappa = 120$ PLT $\kappa = 75$ PLT $\kappa = 750$	$\begin{array}{c} 0.074 \\ 0.054 \\ 0.044 \\ 0.050 \\ 0.062 \\ 0.010 \end{array}$	$1.96 \\ $	not rejected not rejected not rejected not rejected not rejected not rejected

6 Conclusions and Outlook

The present paper provides a substantial extension of the copula methodology which was previously proposed in [9]. We derived parametric approximation formulas for the univariate density functions of the total lengths I_i of both half-trees of the shortest-path tree. Besides, a one-parametric bivariate Gaussian copula has been used to model the correlation structure between the components of the random vector $I = (I_1, I_2)$. Visual validation and the multivariate Wald-Wolfowitz test showed that this approach to model the bivariate distribution of the functional I in shortest-path trees and their corresponding half-trees is suitable to directly simulate random vectors representing the data extracted from the typical segment system S_H^* in telecommunication networks.

In a forthcoming paper [5], we will provide a rigorous proof for the asymptotic distribution of I as the scaling parameter κ tends to ∞ . Additional research topics in future could be the investigation of further, e.g. capacity-related functionals of the shortest-path tree G. Note that studying the asymmetry of the half-trees of Gis an important topic from the telecommunication point of view as knowing the corresponding capacities determines the choice of size for the two biggest cables from higher to lower nodes. For instance, it answers the question whether engineers should use two cables each with capacity of 50% (since the half-trees have more or less the same capacities) or rather a partition of 70% and 30%.

References

- 1. D.J. Daley and D. Vere-Jones. An Introduction to the Theory of Point Processes. Vol. I/II, Springer, New York, 2005/08.
- F. Fleischer, C. Gloaguen, V. Schmidt and F. Voss. Simulation of the typical Poisson-Voronoi-Cox-Voronoi cell. Journal of Statistical Computation and Simulation, 79:939-957, 2009.
- 3. J. H. Friedman and L. C. Rafsky. Multivariate generalizations of the Wald-Wolfowitz and Smirnov two-sample tests. The Annals of Statistics, 7:967-717, 1979.
- 4. C. Gloaguen, F. Voss and V. Schmidt. Parametric distributions of connection lengths for the efficient analysis of fixed access network. Annals of Telecommunications, 66:103-118, 2011.

- 5. C. Hirsch, D. Neuhäuser and V. Schmidt. Asymptotic properties of Euclidean shortest-path trees and applications to telecommunication networks. Working paper (under preparation). 6. J. Illian, A. Penttinen, H. Stoyan and D. Stoyan. Statistical Analysis and Modelling of
- Spatial Point Patterns. J. Wiley & Sons, Chichester, 2008.
- 7. J.-F. Mai and M. Scherer. Simulating Copulas: Stochastic Models, Sampling Algorithms, and Applications. Imperial College Press, London, 2012.
- R. B. Nelsen. An Introduction to Copulas. Springer, New York, 2006.
 D. Neuhäuser, C. Hirsch, C. Gloaguen, and V. Schmidt. A parametric copula approach for modelling shortest-path trees in telecommunication networks. In: A. Dudin and K. Turck (eds.) Analytical and Stochastic Modeling Techniques and Applications. Lecture Notes in Computer Science 7984, Springer, Berlin 2013, 324-336.
- 10. D. Neuhäuser, C. Hirsch, C. Gloaguen and V. Schmidt. On the distribution of typical shortest-path lengths in connected random geometric graphs. Queueing Systems, 71:199-220, 2012.
- 11. D. Ruppert. Statistics and Data Analysis for Financial Engineering. Springer Texts in Statistics, New York, 2010.
- 12. R. Schneider and W. Weil. Stochastic and Integral Geometry. Springer, Berlin, 2008.
- 13. D. Stoyan, W.S. Kendall, and J. Mecke. Stochastic Geometry and its Applications. J. Wiley & Sons, Chichester, 1995.
- 14. F. Voss, C. Gloaguen, F. Fleischer and V. Schmidt. Densities of shortest path lengths in spatial stochastic networks. Stochastic Models, 27:141-167, 2011.
- 15. F. Voss, C. Gloaguen and V. Schmidt. Scaling limits for shortest path lengths along the edges of stationary tessellations. Advances in Applied Probability, 42:936-952, 2010.