

**CLT for the Integrated Square Error
of
Product Density Estimators**

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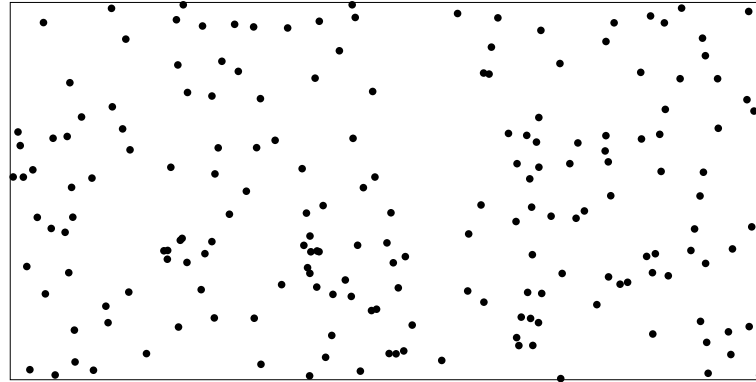
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Outline

- Point processes: basics and notation
- Kernel-type product density estimator
- CLT for the integrated square error of the product density estimator
- Outlook

Point processes – definition



Let \mathcal{N} be the set of all locally finite counting measures on \mathbb{R}^d , and let \mathfrak{N} be the sigma algebra induced by the sets $\{\psi \in \mathcal{N} : \psi(B) = n\}$, $B \in \mathfrak{B}(\mathbb{R}^d)$ (Borel set), $n \in \mathbb{N}_0$.

Definition: A **point process** Ψ in \mathbb{R}^d is a measurable mapping from a probability space $[\Omega, \mathfrak{A}, \mathbb{P}]$ into $[\mathcal{N}, \mathfrak{N}]$. Let $P = \mathbb{P} \circ \Psi^{-1}$ denote the probability measure on $[\mathcal{N}, \mathfrak{N}]$ induced by Ψ , the **distribution of Ψ** , and write $\Psi \sim P$. \square

We only consider point processes Ψ that are simple, i.e., $\Psi \in \mathcal{N}_s = \{\psi \in \mathcal{N} : \psi(\{x\}) \leq 1 \forall x \in \mathbb{R}^d\}$.

Point processes – stationarity and isotropy

Definition: A point process $\Psi \sim P$ is **stationary** if P is translation invariant, i.e.

$$(\Psi(B_1 + \mathbf{x}), \dots, \Psi(B_k + \mathbf{x})) \stackrel{d}{=} (\Psi(B_1), \dots, \Psi(B_k))$$

for all $\mathbf{x} \in \mathbb{R}^d$, $B_1, \dots, B_k \in \mathfrak{B}(\mathbb{R}^d)$, $k \geq 1$. □

Definition: A point process $\Psi \sim P$ is **isotropic** if P is rotation invariant, i.e.

$$(\Psi(UB_1), \dots, \Psi(UB_k)) \stackrel{d}{=} (\Psi(B_1), \dots, \Psi(B_k))$$

for all $B_1, \dots, B_k \in \mathfrak{B}(\mathbb{R}^d)$, $k \geq 1$ and $U \in \text{SO}(d)$. □

Definition: If a point process Ψ is both stationary and isotropic, it is called **motion invariant**. □

We only consider stationary simple point processes.

Moment measure of order k

Definition: $\alpha^{(k)}$ (factorial moment measure of order k)

For all $B_1, \dots, B_k \in \mathfrak{B}(\mathbb{R}^d)$:

$$\alpha^{(k)}(B_1 \times \dots \times B_k) := \mathbb{E} \sum_{\substack{x_1, \dots, x_k \\ \in \text{supp}(\Psi)}}^{\neq} \mathbb{1}_{B_1}(x_1) \cdots \mathbb{1}_{B_k}(x_k)$$

□

"Factorial": $\alpha^{(k)}(B \times \dots \times B) = \mathbb{E} \Psi(B)(\Psi(B) - 1) \cdots (\Psi(B) - k + 1)$

$\alpha^{(1)}$ is called **intensity measure**:

$\alpha^{(1)}(A) = \mathbb{E} \Psi(A) \hat{=}$ mean number of points in $A \in \mathfrak{B}(\mathbb{R}^d)$.

$$\Psi \text{ stationary} \Rightarrow \alpha^{(1)}(\cdot) = \lambda |\cdot|$$

$\lambda := \mathbb{E} \Psi([0, 1]^d) \in (0, \infty)$, the mean number of points in $[0, 1]^d$, is called the **intensity** of the point process Ψ .

Cumulant measure of order k

Definition: $\gamma^{(k)}$ (cumulant measure of order k)

For all $B_1, \dots, B_k \in \mathfrak{B}(\mathbb{R}^d)$:

$$\gamma^{(k)}(B_1 \times \dots \times B_k) := \sum_{\ell=1}^k (-1)^{\ell-1} (\ell-1)! \sum_{\substack{K_1 \cup \dots \cup K_\ell \\ = \{1, \dots, k\}}} \prod_{j=1}^{\ell} \alpha^{(|K_j|)} \left(\prod_{k_j \in K_j} B_{k_j} \right)$$

□

"covariance measure" $\gamma^{(2)}$:

For disjoint $A, B \in \mathfrak{B}(\mathbb{R}^d)$ we have

$$\begin{aligned} \gamma^{(2)}(A \times B) &= \alpha^{(2)}(A \times B) - \alpha^{(1)}(A)\alpha^{(1)}(B) \\ &= \mathbb{E}\Psi(A)\Psi(B) - \mathbb{E}\Psi(A)\mathbb{E}\Psi(B) \\ &= \text{Cov}[\Psi(A), \Psi(B)]. \end{aligned}$$

Reduced measures & densities

Let Ψ be a stationary point process with intensity λ .

Definition: $\alpha_{\text{red}}^{(k)}$ (reduced factorial moment measure of order k)

$$\alpha^{(k)}(B_1 \times \cdots \times B_k) = \lambda \int_{B_k} \alpha_{\text{red}}^{(k)}((B_1 - x) \times \cdots \times (B_{k-1} - x)) dx$$

□

Definition: $\gamma_{\text{red}}^{(k)}$ (reduced cumulant measure of order k)

$$\gamma^{(k)}(B_1 \times \cdots \times B_k) = \lambda \int_{B_k} \gamma_{\text{red}}^{(k)}((B_1 - x) \times \cdots \times (B_{k-1} - x)) dx$$

□

Definition: The k th-order product density $\varrho^{(k)}$ is the Lebesgue density of the k th-order reduced factorial moment measure $\alpha_{\text{red}}^{(k)}$.

□

Definition: The k th-order cumulant density $c^{(k)}$ is the Lebesgue density of the k th-order reduced cumulant measure $\gamma_{\text{red}}^{(k)}$.

□

Poisson processes and Poisson cluster processes – definition

Definition: A point process Ψ is called a **Poisson process** in \mathbb{R}^d with intensity measure Λ iff

- $\Psi(A_1), \dots, \Psi(A_k)$ are independent for disjoint $A_1, \dots, A_k \in \mathfrak{B}(\mathbb{R}^d) \forall k \in \mathbb{N}$
- $\Psi(A) \sim \text{Po}(\Lambda(A))$ for every bounded $A \in \mathfrak{B}(\mathbb{R}^d)$ □

Notation: $\Psi \sim \Pi_\Lambda$

$\Psi \sim \Pi_\Lambda$ is stationary $\Leftrightarrow \Lambda(\cdot) = \lambda|\cdot|$ for some $\lambda > 0$

The distribution of a stationary Poisson process with intensity λ is denoted by Π_λ .

Definition: A **stationary Poisson cluster process** Ψ in \mathbb{R}^d consists of two components: the primary process $\Psi_p \sim \Pi_{\lambda_p}$ ($0 < \lambda_p < \infty$) and the secondary process $\Psi_c \sim P_c$. Each point $x \in \text{supp}(\Psi_p)$ triggers a point process $\Psi_c^{[x]} \sim P_c^{[x]}$ (cluster) that is assumed to be independent of Ψ_p and $\Psi_c^{[y]}$, $y \neq x$, and to have the same distribution as the translated process $T_x \Psi_c$. The condition $\mathbb{E}\Psi_c(\mathbb{R}^d) < \infty$ guarantees the existence of the Poisson cluster process Ψ . □

Brillinger-mixing point processes

Definition: A stationary point process Ψ is called **Brillinger-mixing** iff

$$\mathbb{E}\Psi^k([0, 1]^d) < \infty \quad \text{and} \quad \|\gamma_{\text{red}}^{(k)}\| := \int_{(\mathbb{R}^d)^{k-1}} |\gamma_{\text{red}}^{(k)}(\mathbf{d}\mathbf{x})| < \infty$$

for all $k \geq 2$. □

For example, stationary Poisson cluster processes with the secondary process Ψ_c satisfying $\mathbb{E}\Psi_c^k(\mathbb{R}^d) < \infty$ for all $k \geq 1$, are Brillinger-mixing.

Kernel estimation of the product density

Definition (Krickeberg 1982 [1]): Let the stationary point process Ψ be observed in a convex window W_n satisfying $r(W_n) \rightarrow \infty$ where $r(W_n)$ is the radius of the inscribed sphere of W_n . Let $k : \mathbb{R}^d \rightarrow \mathbb{R}$ be a bounded kernel function with bounded support satisfying $\int_{\mathbb{R}^d} k(x) dx = 1$. Let the bandwidth b_n satisfy $b_n \rightarrow 0$ and $b_n^d |W_n| \rightarrow \infty$.

Define

$$\hat{\varrho}_n(t) := \frac{1}{b_n^d |W_n|} \sum_{x, y \in \text{supp}(\Psi)}^{\neq} \mathbb{1}_{W_n}(x) k\left(\frac{y - x - t}{b_n}\right)$$

as a kernel estimator for $\lambda \varrho(t)$, where $\varrho(t) := \varrho^{(2)}(t)$ is the Lebesgue density of $\alpha_{\text{red}}^{(2)}$. □

Lemma: Let Ψ be a Brillinger-mixing point process and let ϱ be Lipschitz-continuous in $t \in \mathbb{R}^d$. Then we have

$$\mathbb{E} \hat{\varrho}_n(t) \rightarrow \lambda \varrho(t).$$

□

Scaled deviance of the product density estimator (1)

Consider the scaled deviance of the product density estimator,

$$\Delta_n(t) := b_n^{d/2} |\mathbf{W}_n|^{1/2} (\hat{\varrho}_n(t) - \mathbb{E} \hat{\varrho}_n(t)).$$

Theorem (Heinrich 1988 [2]): Let Ψ be a stationary Poisson cluster process with intensity λ . The Lebesgue densities $p^{(2)}$, $p^{(3)}$ and $p^{(4)}$ of the factorial moment measures $\alpha^{(2)}$, $\alpha^{(3)}$ and $\alpha^{(4)}$, respectively, exist and there exist constants C_1, \dots, C_4 such that

$$\begin{aligned} p(u) &:= \int_{\mathbb{R}^d} p^{(2)}(u+x, x) dx \leq C_1, \\ \int_{(\mathbb{R}^d)^2} p^{(3)}(u, u+x, y) d(x, y) &\leq C_2, \\ \int_{\mathbb{R}^d} p^{(3)}(u+x, v+x, y) dx &\leq C_3, \\ \int_{(\mathbb{R}^d)^2} p^{(4)}(u+x, v+y, x, y) d(x, y) &\leq C_4 \end{aligned}$$

for all $u, v \in \mathbb{R}^d$. Furthermore, let the q -tuple $(u_1, \dots, u_q) \in (\mathbb{R}^d)^q$ be chosen such that $u_i \neq u_j$, $u_i \neq -u_j$, $i \neq j$, and every u_i , $i = 1, \dots, q$, is a point of continuity of p .

Scaled deviance of the product density estimator (2)

Recall the scaled deviance of the product density estimator,

$$\Delta_n(t) = b_n^{d/2} |\mathbf{W}_n|^{1/2} (\hat{\varrho}_n(t) - \mathbb{E}\hat{\varrho}_n(t)).$$

Theorem (Heinrich 1988 [2]), continued:

Then we have

$$(\Delta_n(\mathbf{u}_i))_{i=1}^q \xrightarrow{d} \mathbf{N}(\mathbf{0}, \Sigma_q),$$

where $\mathbf{N}(\mathbf{0}, \Sigma_q)$ is a Gaussian vector with covariance matrix $\Sigma_q = (\sigma_{ij})_{i,j=1}^q$, where $\sigma_{ii} = \tau^2 \lambda_{\varrho}(\mathbf{u}_i)$, $\tau^2 := \int_{\mathbb{R}^d} k^2(x) dx$, $i = 1, \dots, q$, and $\sigma_{ij} = 0$, $i \neq j$.

Furthermore, we have

$$\frac{1}{\tau^2} \sum_{i=1}^q \frac{(\Delta_n(\mathbf{u}_i))^2}{\lambda_{\varrho}(\mathbf{u}_i)} \xrightarrow{d} \chi_q^2.$$

□

Integrated square error (ISE)

The integrated square error (ISE) of the kernel estimator $\hat{\varrho}_n$ on a bounded subset $\mathbf{K} \subset \mathbb{R}^d$ satisfying $|\mathbf{K}| > 0$ is

$$I_n(\mathbf{K}) := \int_{\mathbf{K}} (\hat{\varrho}_n(t) - \lambda \varrho(t))^2 dt.$$

For a stationary Poisson process with intensity λ the second-order product density satisfies $\varrho(t) = \lambda$ for all $t \in \mathbb{R}^d$. This entails

$$I_n(\mathbf{K}) = \int_{\mathbf{K}} (\hat{\varrho}_n(t) - \lambda)^2 dt.$$

Because of the asymptotic independence of the components of

$$(\Delta_n(\mathbf{u}_i))_{i=1}^q = \left(b_n^{d/2} |\mathbf{W}_n|^{1/2} (\hat{\varrho}_n(\mathbf{u}_i) - \mathbb{E} \hat{\varrho}_n(\mathbf{u}_i)) \right)_{i=1}^q,$$

for $\mathbf{u}_i \neq \mathbf{u}_j$ we cannot use Heinrich's result for deriving the asymptotic distribution of the ISE.

Poisson processes: mean and variance of the ISE

Lemma: Let Ψ be a stationary Poisson process with intensity λ .

Then the expectation of the ISE satisfies, for $n \rightarrow \infty$,

$$b_n^d |W_n| \mathbb{E} \int_K (\hat{\varrho}_n(t) - \lambda^2)^2 dt = \lambda^2 |K| \int_{\mathbb{R}^d} k^2(y) dy + O(b_n^d),$$

and its variance satisfies

$$\begin{aligned} & \text{Var} \left(b_n^{d/2} |W_n| \int_K (\hat{\varrho}_n(t) - \lambda^2)^2 dt \right) \\ & \rightarrow 2\lambda^4 (|K| + |K \cap \check{K}|) \int_{\mathbb{R}^d} \tilde{k}^2(t) dt, \end{aligned}$$

where $\check{K} := \{x \in \mathbb{R}^d : -x \in K\}$ and $\tilde{k}(t) = \int_{\mathbb{R}^d} k(x)k(x+t)dx$. □

Poisson processes: CLT for the ISE

Theorem 1: Let Ψ be a stationary Poisson process with intensity λ . Let the observation window be of the form $\mathbf{W}_n = [0, n)^d$. Let $I_n(\mathbf{K}) = \int_{\mathbf{K}} (\hat{\varrho}_n(t) - \lambda)^2 dt$.

Then

$$b_n^{d/2} n^d (I_n(\mathbf{K}) - \mathbb{E}I_n(\mathbf{K})) \xrightarrow{d} \mathbf{N} \left(0, 2\lambda^4 (|\mathbf{K}| + |\mathbf{K} \cap \check{\mathbf{K}}|) \int_{\mathbb{R}^d} \tilde{k}^2(t) dt \right).$$

The result still holds when $\mathbb{E}I_n(\mathbf{K})$ is replaced with $\frac{\lambda^2 |\mathbf{K}|}{b_n^{d/2}} \int_{\mathbb{R}^d} k^2(x) dx$. □

Given a realization of $\Psi \sim P$, Theorem 1 can thus be used for testing complete spatial randomness (test problem $H_0 : P = \Pi_\lambda$ vs. $H_1 : P \neq \Pi_\lambda$ with known intensity $\lambda > 0$).

Assumptions

K(d,s) The kernel function k satisfies

$$\int_{\mathbb{R}^d} \mathbf{x}_{i_1} \cdot \dots \cdot \mathbf{x}_{i_\ell} k(\mathbf{x}_1, \dots, \mathbf{x}_d) d(\mathbf{x}_1, \dots, \mathbf{x}_d) = \mathbf{0},$$

for all $i_1, \dots, i_\ell \in \{1, \dots, d\}$, $\ell = 1, \dots, s - 1$ (with $s \geq 2$).

(M1) The second-order product density ϱ is continuous in $\mathbf{K} \oplus \mathbf{b}(\mathbf{0}, \varepsilon)$ for some $\varepsilon > \mathbf{0}$ with bounded partial derivatives of order s .

(M2) The third-order cumulant density $c^{(3)}$ and the third-order product density $\varrho^{(3)}$ exist and are bounded.

(M3) The fourth-order cumulant density $c^{(4)}$ exists and satisfies

$$\int_{\mathbb{R}^d} |c^{(4)}(\mathbf{x}, \mathbf{z}, \mathbf{z} + \mathbf{y})| d\mathbf{z} \leq C < \infty$$

for all $\mathbf{x}, \mathbf{y} \in \mathbf{K} \oplus \mathbf{b}(\mathbf{0}, \varepsilon)$ for some $\varepsilon > \mathbf{0}$.

Brillinger-mixing point processes: mean and variance of the ISE

Lemma 1: Let Ψ be a stationary Brillinger-mixing point process in \mathbb{R}^d with intensity λ . Let the kernel function k satisfy condition $\mathbf{K}(\mathbf{d}, \mathbf{s})$ and let Ψ satisfy the assumptions **(M1)–(M3)**. Then we have, for $n \rightarrow \infty$,

$$b_n^d |W_n| \mathbb{E} \int_K (\hat{\varrho}_n(t) - \lambda \varrho(t))^2 dt \rightarrow \lambda \int_K \varrho(t) dt \int_{\mathbb{R}^d} k^2(x) dx.$$

If, in addition, the bandwidth satisfies $b_n^{3d} |W_n| \rightarrow \infty$ and $b_n^s |W_n| \rightarrow 0$ (thus $s \geq 3d + 1$), then

$$\begin{aligned} & \text{Var} \left(b_n^{d/2} |W_n| \int_K (\hat{\varrho}_n(t) - \lambda \varrho(t))^2 dt \right) \\ & \rightarrow 2\lambda^2 \left(\int_K \varrho^2(t) dt + \int_{K \cap \check{K}} \varrho^2(t) dt \right) \int_{\mathbb{R}^d} \tilde{k}^2(t) dt, \end{aligned}$$

where $\check{K} := \{x \in \mathbb{R}^d : -x \in K\}$ and $\tilde{k}(t) = \int_{\mathbb{R}^d} k(x)k(x+t)dx$. □

Poisson cluster processes: CLT for the ISE

Theorem 2: Let Ψ be a stationary Poisson cluster process with intensity λ and secondary process Ψ_c . Assume $\mathbb{E}\Psi_c^8(\mathbb{R}^d) \leq C < \infty$ to hold for some $C > 0$. Let the observation window be of the form $\mathbf{W}_n = [0, n)^d$. Let $I_n(\mathbf{K}) = \int_{\mathbf{K}} (\hat{\varrho}_n(t) - \lambda \varrho(t))^2 dt$.

Then we have, under the assumptions of Lemma 1,

$$b_n^{d/2} n^d (I_n(\mathbf{K}) - \mathbb{E}I_n(\mathbf{K})) \xrightarrow{d} \mathbf{N} \left(\mathbf{0}, 2\lambda^2 \left(\int_{\mathbf{K}} \varrho^2(t) dt + \int_{\mathbf{K} \cap \tilde{\mathbf{K}}} \varrho^2(t) dt \right) \int_{\mathbb{R}^d} \tilde{k}^2(t) dt \right).$$

The result still holds when $\mathbb{E}I_n(\mathbf{K})$ is replaced with a constant c_n which depends only on the bandwidth b_n , the kernel function k , the set \mathbf{K} and the product density ϱ . \square

Given a realization of $\Psi \sim P$, Theorem 2 can thus be used for testing $H_0 : P = P_0$ vs. $H_1 : P \neq P_0$, where P_0 is the distribution of a Poisson cluster process satisfying the above assumptions with known product density ϱ and intensity λ .

CLT for the ISE – Sketch of the Proof

(1) Prove the CLT for Poisson cluster processes with bounded cluster radius. In this case a CLT for m -dependent point fields (Heinrich 1988 [3]) can be used.

(2) In order to prove the CLT for Poisson cluster processes Ψ with secondary process Ψ_c with unbounded cluster radius, use a "truncation method": Let $\Psi^{(\alpha)}$ be the "truncated" Poisson cluster process, where its secondary process Ψ_c is replaced by the truncated cluster $\Psi_c^{(\alpha)} := \Psi_c \cap b(0, \alpha)$. Due to **(1)**, the CLT for the ISE $I_n^{(\alpha)}(K)$ of $\Psi^{(\alpha)}$ holds.

Showing that for all $\varepsilon > 0$ there exists an $n_0 = n_0(\varepsilon)$ such that

$$\limsup_{\alpha \rightarrow \infty} \sup_{n \geq n_0} \text{Var} \left[b_n^{d/2} n^d \left(I_n^{(\alpha)}(K) - I_n(K) \right) \right] \leq \varepsilon$$

entails the CLT for the ISE $I_n(K)$ of Ψ .

Remarks & outlook

- In the setting of Poisson cluster processes, the theory of m -dependent point fields can be used for deriving a CLT for the ISE. In the case of Brillinger-mixing point processes this is not possible.
Idea: Show the ISE's cumulants of order $k \geq 2$ to converge to zero.
- Modifications of the product density estimator (e.g. edge-correction) should also be considered.
- How large does the observation window W_n have to be, i.e., how many points do we need for a satisfactory approximation from the CLT?

Simulation studies

References

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- [2] Heinrich, L. (1988). Asymptotic Gaussianity of Some Estimators for Reduced Factorial Moment Measures and Product Densities of Stationary Poisson Cluster Processes, *Statistics* **19** 1, 87–106.
- [3] Heinrich, L. (1988). Asymptotic behaviour of an empirical nearest-neighbour distance function for stationary poisson cluster processes, *Mathematische Nachrichten* **136**, 131–148.